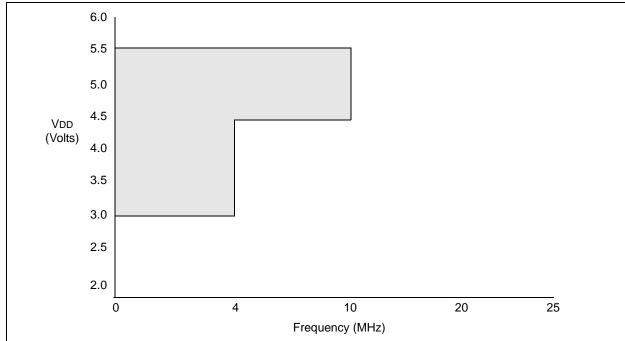


# **PIC12C67X**

## PIC12C67X Rev. A Silicon/Data Sheet Errata

The PIC12C67X (Rev. A) parts you have received conform functionally to the Device Data Sheet (**DS30561**), except for the anomalies described below.

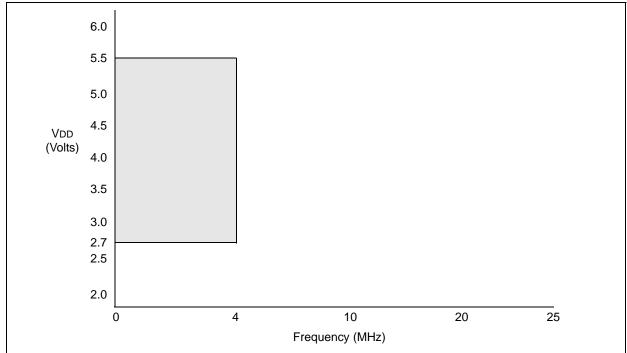
FIGURE 1: PIC12C67X VOLTAGE-FREQUENCY GRAPH,  $-40^{\circ}$ C  $\leq$  Ta  $\leq$  +125 $^{\circ}$ C



Note 1: The shaded region indicates the permissible combinations of voltage and frequency.

2: The maximum rated speed of the part limits the permissible combinations of voltage and frequency. Please reference the Product Identification System section for the maximum rated speed of the parts.

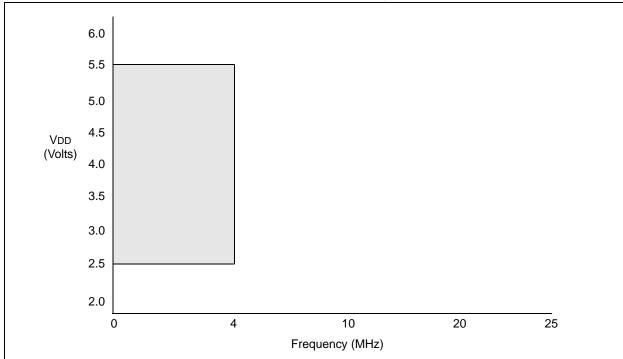
FIGURE 2: PIC12LC67X VOLTAGE-FREQUENCY GRAPH,  $-40^{\circ}$ C  $\leq$  Ta  $\leq$   $0^{\circ}$ C



Note 1: The shaded region indicates the permissible combinations of voltage and frequency.

2: The maximum rated speed of the part limits the permissible combinations of voltage and frequency. Please reference the Product Identification System section for the maximum rated speed of the parts.

FIGURE 3: PIC12LC67X VOLTAGE-FREQUENCY GRAPH, 0°C ≤ TA ≤ +70°C



Note 1: The shaded region indicates the permissible combinations of voltage and frequency.

**2:** The maximum rated speed of the part limits the permissible combinations of voltage and frequency. Please reference the Product Identification System section for the maximum rated speed of the parts.

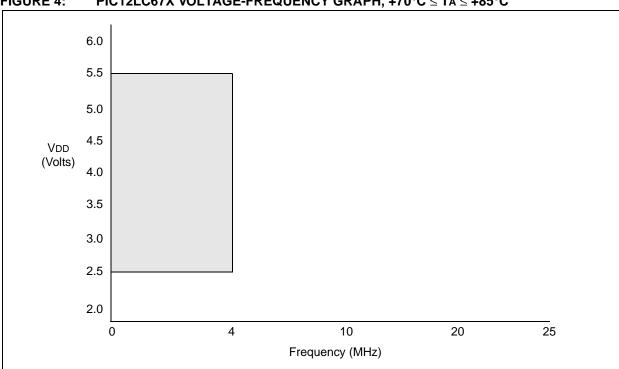


FIGURE 4: PIC12LC67X VOLTAGE-FREQUENCY GRAPH,  $+70^{\circ}$ C  $\leq$  Ta  $\leq$   $+85^{\circ}$ C

Note 1: The shaded region indicates the permissible combinations of voltage and frequency.

2: The maximum rated speed of the part limits the permissible combinations of voltage and frequency. Please reference the Product Identification System section for the maximum rated speed of the parts.

### Clarifications/Corrections to the Data Sheet:

In the Device Data Sheet (DS30561**B**), the following clarifications and corrections should be noted.

1. Module: Register Summary (OSCCAL)

In Section 4.0, corrections for the Special Function Register Summary, Table 4-1, are shown.

### TABLE 4-1: PIC12C67X SPECIAL FUNCTION REGISTER SUMMARY

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on Power-on Reset	Value on all other RESETS <sup>(3)</sup>
Bank 1											
8Fh	OSCCAL	CAL5	CAL4	CAL3	CAL2	CAL1	CAL0	-	1	1000 00	uuuu uu

Legend: x = unknown, u = unchanged, q = value depends on condition, - = unimplemented read as '0'. Shaded locations are unimplemented, read as '0'.

- Note 1: These registers can be addressed from either bank.
  - 2: The upper byte of the program counter is not directly accessible. PCLATH is a holding register for the PC<12:8> whose contents are transferred to the upper byte of the program counter.
  - 3: Other (non Power-up) Resets include external RESET through MCLR and Watchdog Timer Reset.
  - 4: The IRP and RP1 bits are reserved on the PIC12C67X; always maintain these bits clear.
  - 5: The SCL (GP7) and SDA (GP6) bits are unimplemented on the PIC12C671/672 and read as '0'.

### 2. Module: OSCCAL Register

Correction for the "OSCCAL" Register, Section 4.2.2.7, is shown.

#### 4.2.2.7 OSCCAL REGISTER

The Oscillator Calibration (OSCCAL) Register is used to calibrate the internal 4 MHz oscillator. It contains six bits for calibration. Increasing the value increases the frequency.

#### **REGISTER 4-7: OSCCAL REGISTER (ADDRESS 8Fh)**

R/W-1	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0
CAL5	CAL4	CAL3	CAL2	CAL1	CAL0	_	_
hit 7							hit 0

bit 7-2 CAL<5:0>: Calibration

bit 1-0 Unimplemented: Read as '0'

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented b	oit, read as '0'
- n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

### 3. Module: GPIO Register

Clarification to the "GPIO", Section 5.1 is provided. New I/O drawings were added.

#### 5.1 **GPIO**

GPIO is an 8-bit I/O register. Only the low order 6 bits are used (GP<5:0>). Bits 6 and 7 (SDA and SCL, respectively) are used by the EEPROM peripheral on the PIC12CE673/674. Refer to Section 6.0 and Appendix B for use of SDA and SCL. Please note that GP3 is an input only pin. The configuration word can set several I/O's to alternate functions. When acting as alternate functions, the pins will read as '0' during port read.

Pins GP0, GP1 and GP3 can be configured with weak pull-ups and also with interrupt-on-change. The interrupt on change and weak pull-up functions are not pin selectable. If pin 4, (GP3), is configured as MCLR, a weak pull-up is always on. Interrupt-on-change for this pin is not set and GP3 will read as '0'. Interrupt-on-change is enabled by setting bit GPIE, INTCON<3>.

The interrupt can wake the device from SLEEP. The user, in the interrupt service routine, can clear the interrupt in the following manner:

- Any read or write of GPIO will end the mismatch condition.
- b) Clear flag bit GPIF.

A mismatch condition will continue to set flag bit GPIF. Reading GPIO will end the mismatch condition and allow flag bit GPIF to be cleared.

Note that external oscillator use overrides the GPIO functions on GP4 and GP5.

### FIGURE 5-1: **GP0 and GP1 Block Diagram**

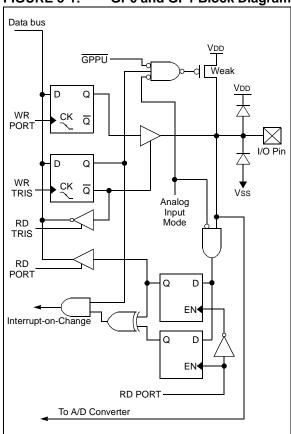


FIGURE 5-2: **GP2 Block Diagram** 

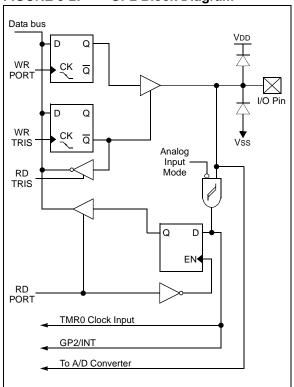


FIGURE 5-4: **GP4 Block Diagram** 

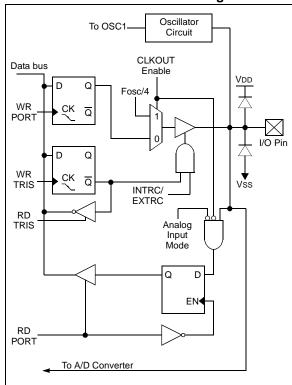


FIGURE 5-3: **GP3 Block Diagram** 

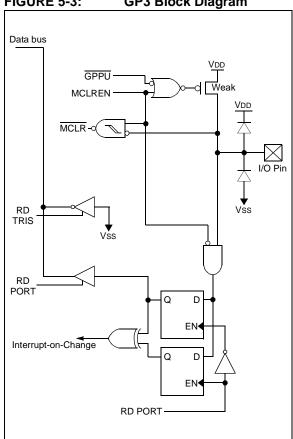
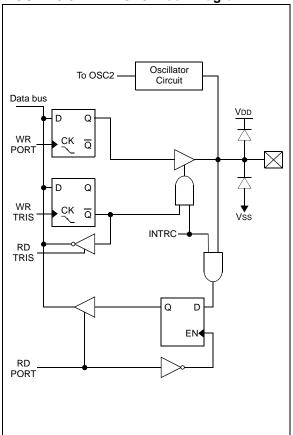


FIGURE 5-5: **GP5 Block Diagram** 



### 4. Module: OSCCAL (Oscillator)

Corrections for the Internal 4 MHz RC Oscillator, Section 9.2.5, are shown.

### 9.2.5 INTERNAL 4 MHz RC OSCILLATOR

OSCCAL, when written to with the calibration value, will "trim" the internal oscillator to remove process variation from the oscillator frequency. Only bits<7:2> of OSCCAL are implemented, and bits<1:0> should be written as 0 for compatibility with future devices. The oscillator calibration location is not code protected.

### 5. Module: Initialization Condition (OSCCAL)

Corrections for Section 9.0, Initialization Conditions for all registers, Table 9-7, are shown.

TABLE 9-7: INITIALIZATION CONDITIONS FOR ALL REGISTERS

Register	Power-on Reset	Power-on Reset MCLR Resets WDT Reset	
OSCCAL	1000 00	uuuu uu	uuuu uu

Legend: u = unchanged, x = unknown, - = unimplemented bit, read as '0', q = value depends on condition.

- Note 1: One or more bits in INTCON and PIR1 will be affected (to cause wake-up).
  - 2: When the wake-up is due to an interrupt and the GIE bit is set, the PC is loaded with the interrupt vector (0004h).
  - **3:** See Table 9-5 for RESET value for specific condition.
  - 4: If wake-up was due to A/D completing then bit 6 = 1, all other interrupts generating a wake-up will cause bit 6 = u.
  - 5: If wake-up was due to A/D completing then bit 3 = 0, all other interrupts generating a wake-up will cause bit 3 = u.

Engineering Samples for the PIC12C671/2 may or may not follow this operational clarification for the OSCCAL register.

DC CHARACTERISTICS

### 6. Module: DC Characteristics

Corrections for the DC Characteristics, Sections 12.3 and 12.4 are shown.

# 12.3 DC CHARACTERISTICS: PIC12C671/672 (Commercial, Industrial, Extended) PIC12CE673/674 (Commercial, Industrial, Extended)

Standard Operating Conditions (unless otherwise specified)

Operating temperature  $0^{\circ}C \leq TA \leq +70^{\circ}C$  (commercial)

 $-40^{\circ}\text{C} \le \text{TA} \le +85^{\circ}\text{C} \text{ (industrial)}$ 

-40°C  $\leq$  TA  $\leq$  +125°C (extended)

Operating voltage VDD range as described in DC spec Section 12.1 and Section 12.2

	Section 12.2.										
Param	Characteristic	Sym	Min	Typ†	Max	Units	Conditions				
No.											
	Input Leakage Current (Notes 2, 3)										
		lı∟									
D061	GP3/MCLR (Note 5)		8	130	250	μΑ	$Vss \le Vpin \le Vdd$				
D061A	GP3/MCLR (Note 6)				<u>+</u> 5	μΑ	$Vss \le Vpin \le Vdd$				
D070	GPIO weak pull-up current (Note 4)	IPUR	50	250	400	μΑ	VDD = 5V, VPIN = VSS				

- † Data in "Typ" column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.
- Note 1: In EXTRC oscillator configuration, the OSC1/CLKIN pin is a Schmitt Trigger input. It is not recommended that the PIC12C67X be driven with external clock in RC mode.
  - 2: The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.
  - 3: Negative current is defined as coming out of the pin.
  - 4: Does not include GP3. For GP3 see parameters D061 and D061A.
  - 5: This spec. applies to GP3/MCLR configured as external MCLR and GP3/MCLR configured as input with internal pull-up enabled.
  - 6: This spec. applies when GP3/MCLR is configured as an input with pull-up disabled. The leakage current of the MCLR circuit is higher than the standard I/O logic.

# 12.4 DC CHARACTERISTICS: PIC12LC671/672 (Commercial, Industrial) PIC12LCE673/674 (Commercial, Industrial)

DC CHA	RACTERISTICS	Standard Operating Conditions (unless otherwise specified)  Operating temperature $0^{\circ}C \le TA \le +70^{\circ}C$ (commercial) $-40^{\circ}C \le TA \le +85^{\circ}C$ (industrial)  Operating voltage VDD range as described in DC spec Section 12.1 and Section 12.2.						
Param	Characteristic	Sym	Min	Typ†	Max	Units	Conditions	
No.								
	Input Leakage Current (Notes 2, 3)							
		lı∟						
D061	GP3/MCLR (Note 5)		8	130	250	μΑ	$Vss \le VPIN \le VDD$	
D061A	GP3/MCLR (Note 6)				<u>+</u> 5	μΑ	Vss ≤ Vpin ≤ Vdd	
D070	GPIO weak pull-up current (Note 4)	Ipur	50	250	400	μΑ	VDD = 5V, VPIN = VSS	

- Data in "Typ" column is at 5V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested
- Note 1: In EXTRC oscillator configuration, the OSC1/CLKIN pin is a Schmitt Trigger input. It is not recommended that the PIC12C67X be driven with external clock in RC mode.
  - 2: The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.
  - 3: Negative current is defined as coming out of the pin.
  - 4: Does not include GP3. For GP3 see parameters D061 and D061A.
  - 5: This spec. applies to GP3/MCLR configured as external MCLR and GP3/MCLR configured as input with internal pull-up enabled.
  - 6: This spec. applies when GP3/MCLR is configured as an input with pull-up disabled. The leakage current of the MCLR circuit is higher than the standard I/O logic.

### 7. Module: GPIO Register

Corrections for the GPIO pull-up resistor ranges are shown in Table 12-6.

TABLE 12-6: GPIO PULL-UP RESISTOR RANGES

VDD (Volts)	Temperature (°C)	Min	Тур	Max	Units
		GP0	/GP1		
2.5	-40	38K	42K	63K	Ω
	-40 38K 25 42K 85 42K 125 50K -40 15K 25 18K 85 19K 125 22K  -40 65K 25 80K 85 85K 125 100K -40 50K	42K	48K	63K	Ω
	85	42K	49K	63K	Ω
	125	50K	55K	63K	Ω
5.5	-40	15K	17K	20K	Ω
	25	18K	20K	23K	Ω
	85	19K	22K	25K	Ω
	125	22K	24K	28K	Ω
		GP	3(1)		
2.5	-40	65K	80K	850K	Ω
	25	80K	100K	1150K	Ω
	85	85K	110K	1300K	Ω
	125	100K	120K	1500K	Ω
5.5	-40	50K	60K	600K	Ω
	25	60K	65K	750K	Ω
	85	65K	80K	900K	Ω
	125	75K	90K	990K	Ω

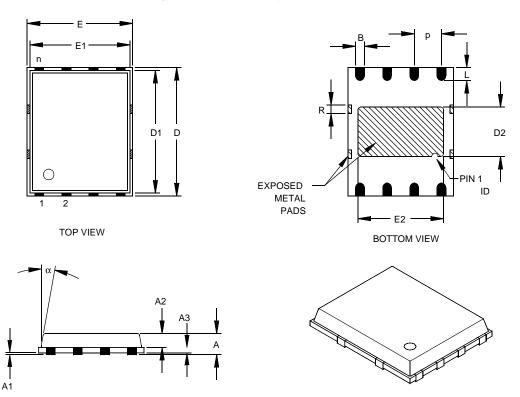
<sup>\*</sup> These parameters are characterized but not tested.

Note 1: The weak pull-up resistor and associated current for the GP3/MCLR pin is non-linear when the respective pin voltage is less than VDD - 1.0V. See parameter D061 for GP3/MCLR pin current specifications.

### 8. Module: PACKAGING INFORMATION

Added 8-Lead Plastic Micro Leadframe Package (MF) and (MLF-S).

### 8-Lead Plastic Micro Leadframe Package (MF) 6x5 mm Body (MLF-S)



	Units				MI	LLIMETERS*	
Dimens	sion Limits	MIN	NOM	MAX	MIN	NOM	MAX
Number of Pins	n		8			8	
Pitch	р		.050 BSC			1.27 BSC	
Overall Height	А		.033	.039		0.85	1.00
Molded Package Thickness	A2		.026	.031		0.65	0.80
Standoff	A1	.000	.0004	.002	0.00	0.01	0.05
Base Thickness	A3		.008 REF.		0.20 REF.		
Overall Length	E	.194 BSC			4.92 BSC		
Molded Package Length	E1		.184 BSC			4.67 BSC	
Exposed Pad Length	E2	.152	.158	.163	3.85	4.00	4.15
Overall Width	D		.236 BSC			5.99 BSC	
Molded Package Width	D1		.226 BSC			5.74 BSC	
Exposed Pad Width	D2	.085	.091	.097	2.16	2.31	2.46
Lead Width	В	.014	.016	.019	0.35	0.40	0.47
Lead Length	L	.020	.024	.030	0.50	0.60	0.75
Tie Bar Width	R		.014			.356	
Mold Draft Angle Top	α			12°			12°

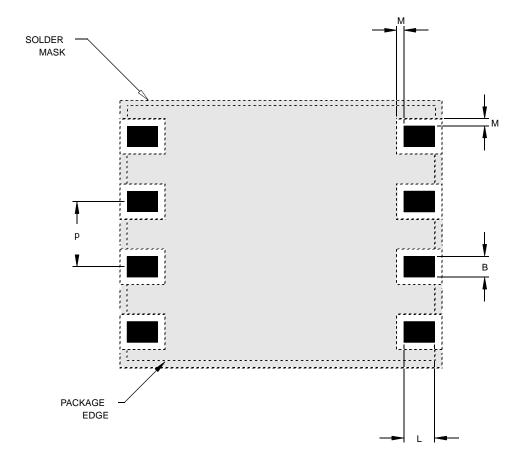
<sup>\*</sup>Controlling Parameter

Notes:

Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" (0.254mm) per side. JEDEC equivalent: pending

Drawing No. C04-113

## 8-Lead Plastic Micro Leadframe Package (MF) 6x5 mm Body (MLF-S)



	Units		INCHES		MILLIMETERS*			
Dimension Limits		MIN	NOM	MAX	MIN	NOM	MAX	
Pitch	р	.050 BSC 1.27 BSC						
Pad Width	В	.014	.016	.019	0.35	0.40	0.47	
Pad Length	L	.020	.024	.030	0.50	0.60	0.75	
Pad to Solder Mask	М	.005		.006	0.13		0.15	

\*Controlling Parameter

Drawing No. C04-2113

## **PIC12C67X**

### **REVISION HISTORY**

### Rev A Document (2/01)

Original errata document, which includes Figures 1, 2, and 3.

### Rev B Document (6/00)

Under the Clarifications/Corrections, Items 1 through 7 were added.

### Rev C Document (11/01)

Added Figure 1 and renumbered figures accordingly.

Under the Clarifications/Corrections, added Figures 5-1 through 5-5 added to Item 3. Item 8, added 8-Lead Plastic Micro Leadframe Package (MF/MLF-S).

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